

IKP11

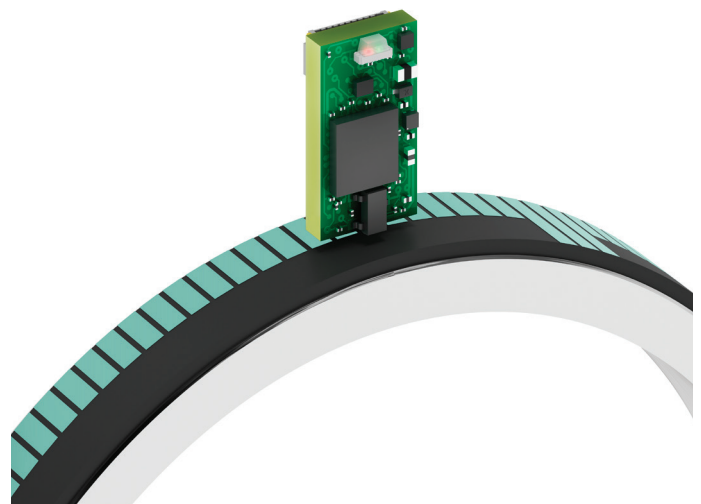
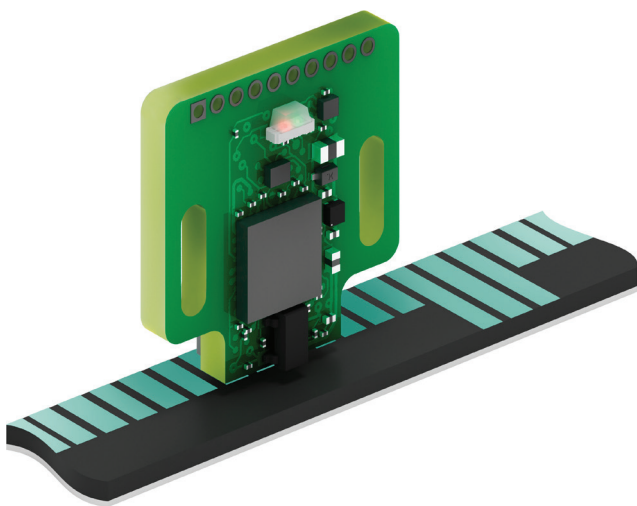
Incremental Magnetic Sensing Head

With the compact incremental magnetic sensing head IKP11, BOGEN offers superb performance in a small form factor. If space is decisive IKP11 is an excellent choice. IKP11 is the preferred choice for automation, instrumentation and motion control applications. In combination with BOGEN precision scales, measurement solutions for almost every application can be custom-tailored.

compact
size

rotary and
linear
applications

scales with or
without
index



Features and Benefits

- all important operating parameters can be reconfigured by the user at any time
- LEDs indicating input signal quality, error and configuration mode
- extra small size for implementation in confined spaces
- wide range of resolution options available
- no wear due to non-contact operation

Features

resolution	0.020 to 500µm, depending on pole pitch and interpolation
energy consumption (without load)	tbc
operating temperature	- 40 to + 125 °C
storage temperature	- 40 to + 150 °C
adjustable parameters	resolution, maximum output frequency, signal conditioning, filter characteristic, pole pitch, error masks, ABZ or UVM output

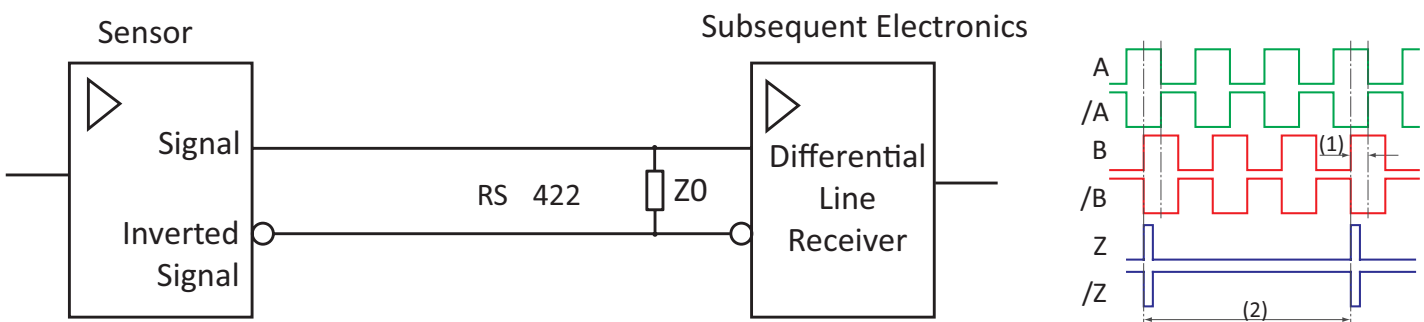
Sensing Head Variants

pole pitch (mm)	1, 2, 2.54, 5
reference	periodic reference signal from the pole pitch or from reference marks, requires 2-track magnetic tape with incremental track and reference track
supply voltage	5 V ± 10% [3.3 V on request]
interface (without load)	RS422 (0 to Vcc) push-pull TTL (0 to Vcc)

Output Circuit

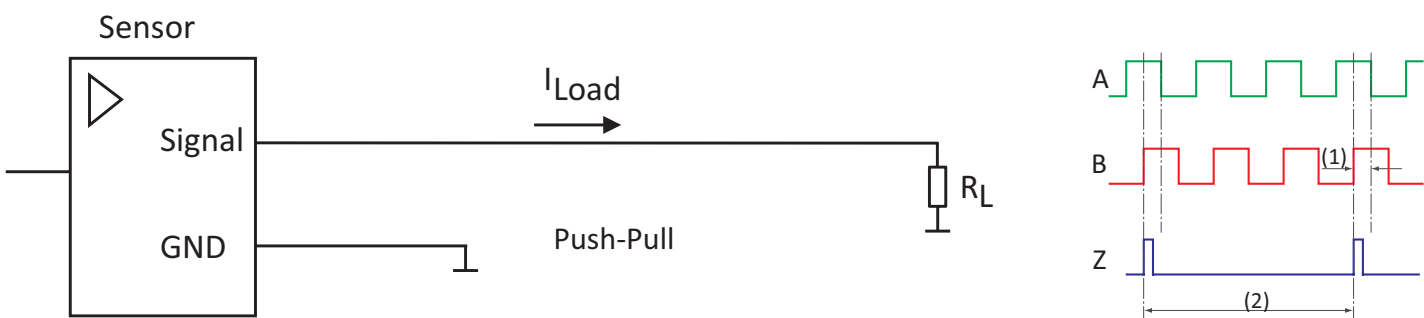
RS422

load resistor Z0 = 120 Ω at receiving end



Push-Pull (TTL)

maximum of 50 mA per channel at a supply voltage of 5 V



(1) phase shift A and B 90° ± 10° electrical

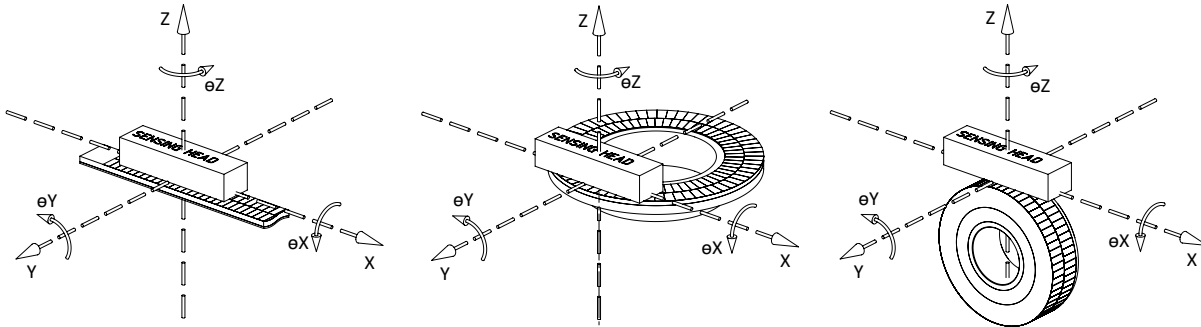
(2) signal period depending on the reference track pattern

Z length default is 4 counts

Output Signals

signals	A, /A, B, /B, Z, /Z; optional: U, /U, V, /V, W, /W
signal error indicator	red LED shines, if device overheats all outputs are switched off

Installation Tolerances



	pole pitch			
	1 mm	2 mm	2.54 mm	5 mm
Z	0.1 to 0.5 mm	0.1 to 1.0 mm	0.1 to 1.25 mm	0.1 to 2.5 mm
Y	0.5 mm	0.5 mm	0.5 mm	0.5 mm
θ_Y	1 °	1 °	1 °	1 °
θ_X	3 °	3 °	3 °	3 °
θ_Z	3 °	3 °	3 °	3 °

Further Selection (Ordering Parameters)

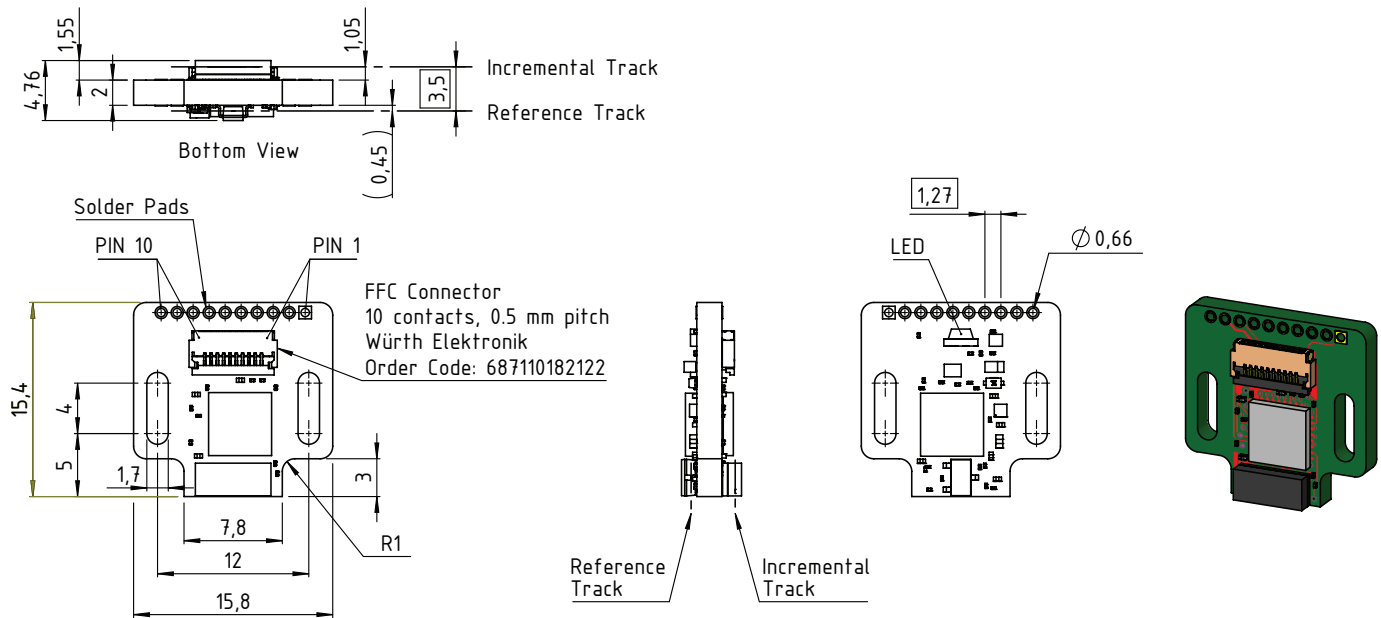
pole pitch P [mm]				resolution R [μm]	resolution Rdpi [dpi]	maximum output frequency per channel F [kHz]					
1	2	2.54 (0.1 in)	5			4000	2500	1000	500	100	50
			x	1250	20.32	100	100	100	100	100	100
	x		x	500	50.8	100	100	100	100	100	90
x	x		x	200	127	100	100	100	100	72	36
x	x		x	100	254	100	100	100	100	36	18
	x			80	317.5	100	100	100	100	28.8	14.4
x	x		x	62.5	406.4	100	100	100	100	22.5	11.25
x	x		x	50	508	100	100	100	90	18	9
x	x		x	40	635	100	100	100	72	14.4	7.2
x	x		x	25	1016	100	100	90	45	9	4.5
x	x	x	x	20	1270	100	100	72	36	7.2	3.6
x	x	x	x	12.5	2032	100	100	45	22.5	4.5	2.25
x	x	x	x	10	2540	100	90	36	18	3.6	1.8
x	x	x	x	5	5080	72	45	18	9	1.8	0.9
x	x	x	x	4	6350	57.6	36	14.4	7.2	1.44	0.72
x	x	x	x	2.5	10160	36	22.5	9	4.5	0.9	0.45
x	x	x	x	2	12700	28.8	18	7.2	3.6	0.72	0.36
x	x	x	x	1	25400	14.4	9	3.6	1.8	0.36	0.18
x	x	x	x	0.5	50800	7.2	4.5	1.8	0.9	0.18	0.09
x	x	x	x	0.25	101600	3.6	2.25	0.9	0.45	0.09	0.045
x	x	x	x	0.125	203200	1.8	1.125	0.45	0.225	0.045	0.0225
x	x	x		0.05	508000	0.72	0.45	0.18	0.09	0.018	0.009
x	x			0.02	1270000	0.288	0.18	0.072	0.036	0.0072	0.0036

table 1: maximum output frequency and speed as a function of pole pitch and resolution

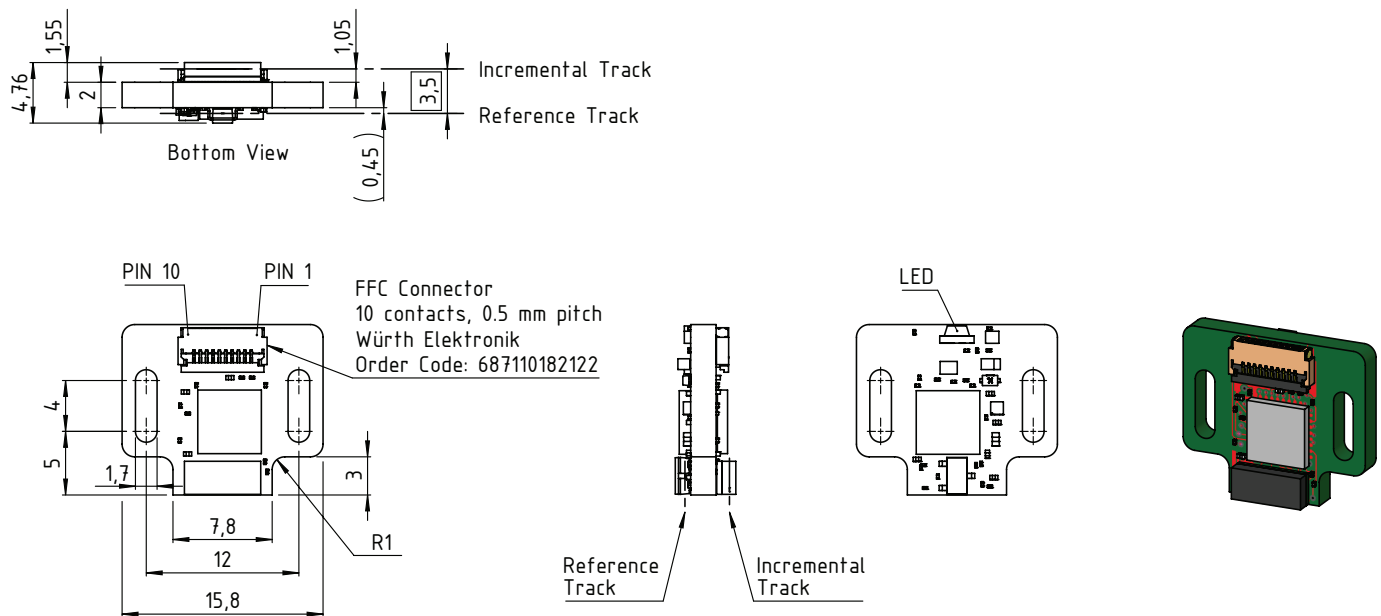
R	resolution (resolution is post quadrature), $R = P / R_f$	F	highest frequency of an output signal under all conditions
P	pole pitch, available 0.5, 1, 2, 2.54, 5 mm	V_{max}	highest allowed movement speed V_{max} is the smaller value resulting from the formulas (- 10 %): $V_{max1} = 4 * F * R$ and $V_{max2} = P * 50 \text{ kHz}$
R_f	resolution factor (resolution factor available from 4 to 65536 in integer increments of one)	Rdpi	resolution [dpi], $Rdpi = 25400 / R$

Dimensions

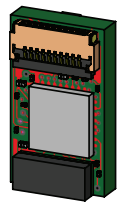
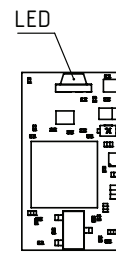
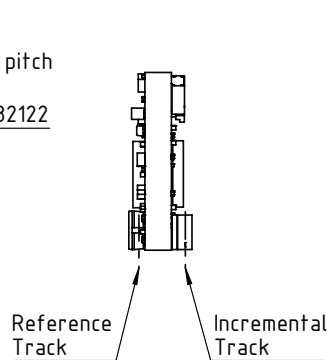
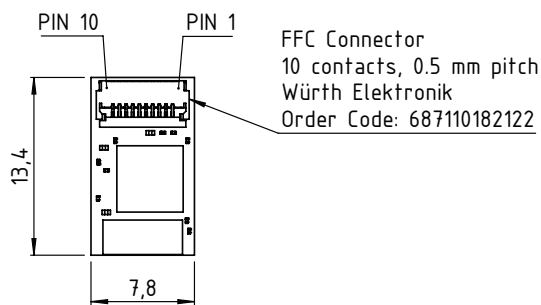
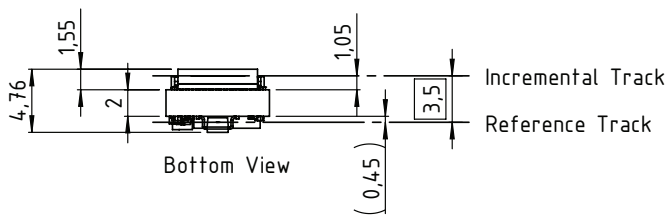
Option C1



Option C2



Option C3



pin no.	1	2	3	4	5	6	7	8	9	10
signal	!PROG	SD0	/Z	Z	/B	B	/A	A	V+	V-

LED Signaling

The RGB-LED of the IKP11 lights blue if the head is in programming mode. It lights red if there is an error. Error types activating the LED can be configured. LED lights green to show an active input signal, the brightness indicates the quality of the input signal.

Programming Mode

The user may change the configuration of the IKP11 by setting it into programming mode. The 5V supply version of the IKP11 is set into programming mode by holding the !PROG input LOW. The 3V supply version overdrives A and /A outputs.

Magnetic Sensing Head Order Code Parameters

IKP11 - Z - P - D - R - F - C

		code	explanation ⁽⁶⁾
Z	reference signal ⁽⁷⁾	Z1. ...	periodic reference signal from the pole pitch, length of reference signal ... counts ⁽⁸⁾
		Z2. ...	from reference marks, requires 2-track magnetic tape with incremental track and reference track, length of index signal 1, 2 or 4 counts ⁽⁸⁾
P	pole pitch [mm]	P1	1 mm
		P2	2 mm
		P2.54	2.54 mm
		P5	5 mm
D	interface	D1	RS422 ABZ
		D2	RS422 UVW
		D3	TTL ABZ
		D4	TTL UVW
R	resolution [µm]	R0.5	0.5 µm resolution, standard for a pole pitch of 1 mm
		R1	1 µm resolution, standard for a pole pitch of 2 mm
		R...	other non-default resolutions, see section "Resolution and Speed" in table 1 on page 3
F	maximum output frequency per channel [kHz]	F1000	output frequency 1000 kHz
		F ...	other non-default output frequencies, see section "Resolution and Speed" in table 1 on page 3
C	connector	C1	PCB 15.8 x 15.4 with FFC connector and solder pads, with mounting option for M1.6 screws
		C2	PCB 15.8 x 13.4 with FFC connector, with mounting option for M1.6 screws
		C3	PCB 7.8 x 13.4 with FFC connector

⁽⁶⁾ default parameters are bold

⁽⁷⁾ if no index signal is needed, please do not connect pin "Z" and "/Z" on delivered connector

⁽⁸⁾ length of index signal available from 1 to 4

Optional Accessories

FFC cable

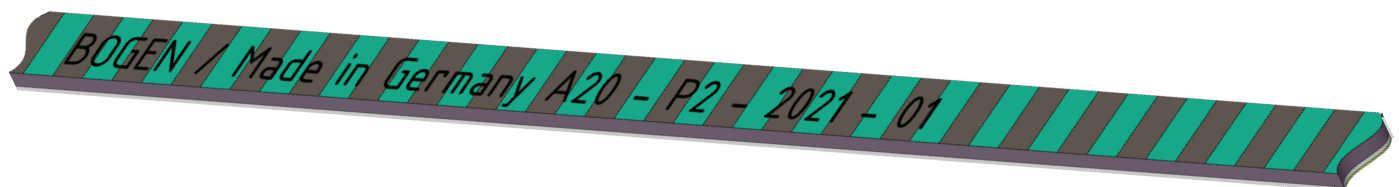
article no.	cable length (mm)	order code
00058728	100	KABL-FFC-P0.5x10-L100
00059056	300	KABL-FFC-P00.5x10-L300

Linear and Rotary Scales

- LMS: linear magnetic scale, from a few millimeters to many meters
- LMSBI: linear magnetic scale bar incremental for high accuracy applications
- RMSI: rotary magnetic scale incremental, in diameters from 10 mm to 1 m
- standard scale width (with reference track): 8 mm and 10 mm; 6 mm on request
- available scale accuracy classes: A3, A10, A20, A40, A100
- available pole pitches: 1 mm, 2 mm, 2.54 mm, 5 mm

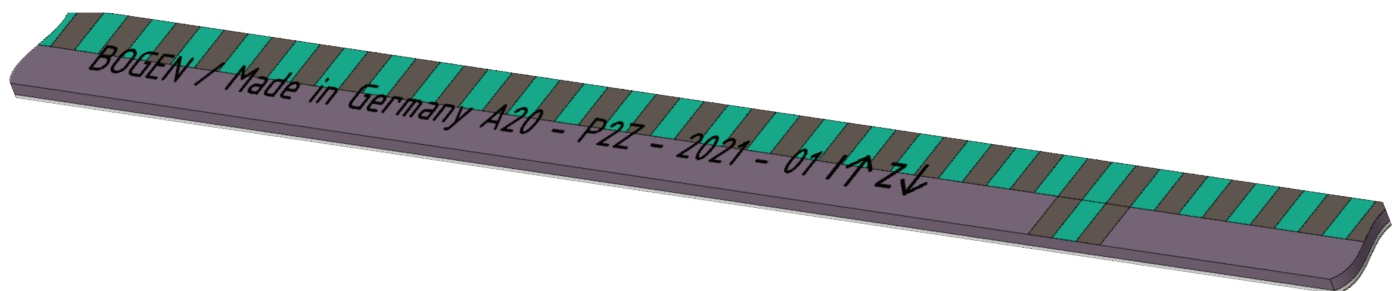
LMS Linear Magnetic Scales Order Code Examples

LMS-I1-L1000-W10-A20-K	linear magnetic scale number of tracks: 1 track1: incremental 1 mm pole pitch accuracy class: $\pm 20 \mu\text{m/m}$ total width: 10 mm total height: 1.43 mm total length: 1000 mm usable measuring length: 990 mm without cover tape with adhesive tape with BOGEN standard imprint
LMS-I2-L1000-W10-A20-K	linear magnetic scale number of tracks: 1 track1: Incremental 2 mm pole pitch Accuracy class: $\pm 20 \mu\text{m/m}$ total width: 10 mm total height: 1.43 mm total length: 1000 mm usable measuring length: 990 mm without cover tape with adhesive tape with BOGEN standard imprint



LMS Linear Magnetic Scales Order Code Exmpl

LMS2-I1-Z-L1000-W10-A20-K	linear magnetic scale number of tracks: 2 track1: Incremental 1 mm pole pitch, 5 mm track width track2: Reference NSN reference every/at XX mm / at center, 5 mm track width accuracy class: $\pm 40 \mu\text{m/m}$ total width: 10 mm total height: 1.43 mm total length: 1000 mm usable measuring length: 990 mm without cover tape with adhesive tape with BOGEN standard imprint
LMS2-I2-Z-L1000-W10-A20-K	linear magnetic scale number of tracks: 2 track1: Incremental 2 mm pole pitch, 5 mm track width track2: Reference NSN reference every/at XX mm / at center, 5 mm track width accuracy class: $\pm 40 \mu\text{m/m}$ total width: 10 mm total height: 1.43 mm total length: 1000 mm usable measuring length: 990 mm without cover tape with adhesive tape with BOGEN standard imprint



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